

# Homework 10 Solutions

ECON 441: Introduction to Mathematical Economics

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## Exercise 12.2

1. (a)  $z = xy$  s.t.  $x + 2y = 2$

Setting up the Lagrangian:

$$L(x, y, \lambda) = xy + \lambda(2 - x - 2y)$$

First-order conditions (F.O.C.s):

$$\frac{dL}{dx} = y - \lambda = 0 \quad (1)$$

$$\frac{dL}{dy} = x - 2\lambda = 0 \quad (2)$$

$$\frac{dL}{d\lambda} = 2 - x - 2y = 0 \quad (3)$$

From (1) and (2),  $y = \lambda$  and  $x = 2\lambda$ , so

$$\frac{y}{x} = \frac{\lambda}{2\lambda} \rightarrow x = 2y$$

Pugging in  $x = 2y$  in (3):

$$2 - x - x = 0 \rightarrow x = 1$$

Stationary point:  $x^* = 1, y^* = 1/2$ . Also note that from (1),  $\lambda^* = y^* = 1/2$ .

(b)  $2 = x(y + 4)$  s.t.  $x + y = 8$

Lagrangian function:

$$L(x, y, \lambda) = x(y + 4) + \lambda(8 - x - y)$$

First-order conditions (F.O.C.s):

$$L_x = y + 4 - \lambda = 0 \quad (1)$$

$$L_y = x - \lambda = 0 \quad (2)$$

$$L_\lambda = 8 - x - y = 0 \quad (3)$$

From equations (1) and (2):

$$\frac{y + 4}{x} = \frac{\lambda}{\lambda} \rightarrow y + 4 = x$$

Plugging  $x = y + 4$  in equation (3):

$$8 - y - 4 - y = 0 \rightarrow y^* = 2$$

Stationary point:  $x^* = y^* + 4 = 6$ ,  $y^* = 2$ . Also note,  $\lambda^* = x^* = 6$ .

(c)  $f(x, y) = x - 3y - xy$  s.t.  $x + y = 6$

Lagrangian function :

$$L(x, y, \lambda) = x - 3y - xy + \lambda(6 - x - y)$$

First-order conditions (F.O.C.s):

$$\frac{dL}{dx} = 1 - y - \lambda = 0 \quad (1)$$

$$\frac{dL}{dy} = -3 - x - \lambda = 0 \quad (2)$$

$$\frac{dL}{d\lambda} = 6 - x - y = 0 \quad (3)$$

From equations (1) and (2):

$$1 - y = -3 - x \rightarrow y = x + 4$$

Plugging in (3):

$$6 - x - x - 4 = 2 - 2x = 0 \rightarrow x = 1$$

Stationary point:  $x^* = 1, y^* = 5$

Lagrange multiplier,  $\lambda^* = 1 - y^* = -4$

(d)  $z = 7 - y + x^2$  s.t.  $x + y = 0$

Lagrangian function:

$$L(x, y, \lambda) = 7 - y + x^2 + \lambda(-x - y)$$

First-order conditions (F.O.C.s):

$$L_x = 2x - \lambda = 0 \quad (1)$$

$$L_y = -1 - \lambda = 0 \quad (2)$$

$$L_\lambda = -x - y = 0 \quad (3)$$

From equation (2),  $\lambda^* = -1$  From equation (1),  $x^* = \frac{\lambda^*}{2} = -\frac{1}{2}$  From equation (3),  $y^* = -x^* = \frac{1}{2}$

So the Stationary point:  $(x^*, y^*) = \left(-\frac{1}{2}, \frac{1}{2}\right)$

2. Suppose we are interested in finding the optimal value of  $f(x, y)$  subject to the constraint  $g(x, y) = c$ . We would start by setting up the Lagrangian function:

$$L(x, y, \lambda) = f(x, y) + \lambda(c - g(x, y))$$

At the optimizing point  $(x^*, y^*)$ , the following first-order conditions hold:

$$L_x(x^*, y^*, \lambda^*) = f_x(x^*, y^*) - \lambda^* g_x(x^*, y^*) = 0 \quad (1)$$

$$L_y(x^*, y^*, \lambda^*) = f_y(x^*, y^*) - \lambda^* g_y(x^*, y^*) = 0 \quad (2)$$

$$L_\lambda(x^*, y^*, \lambda^*) = c - g(x^*, y^*) = 0 \quad (3)$$

Now note that implicitly the optimal inputs  $x^*$  and  $y^*$  depend on  $c$ . So we could express  $x^*$  and  $y^*$  as functions of  $c$ , i.e.,  $x^*(c)$  and  $y^*(c)$ . Then optimal value of  $f$  is given by  $f(x^*(c), y^*(c))$ .

Now, say, we want to know how the optimal value of  $f$  changes if we relax

the constraint i.e. if we increase  $c$  slightly. To find this we can differentiate  $f(x^*(c), y^*(c))$  with respect to  $c$ , then by chain-rule:

$$\frac{d}{dc} f(x^*(c), y^*(c)) = f_x(x^*, y^*) \cdot \frac{dx^*}{dc} + f_y(x^*, y^*) \frac{dy^*}{dc} \quad (4)$$

Now note that from (1) and (2), we have  $f_x(x^*, y^*) = \lambda^* g_x(x^*, y^*)$  and  $f_y(x^*, y^*) = \lambda^* g_y(x^*, y^*)$ . Plugging these terms in equation (4), we get:

$$\frac{d}{dc} f(x^*(c), y^*(c)) = \lambda^* \underbrace{\left[ g_x(x^*, y^*) \cdot \frac{dx^*}{dc} + g_y(x^*, y^*) \frac{dy^*}{dc} \right]}_{=1}$$

The term in the parenthesis is 1 because if we take the derivative of (3) with respect to  $c$ , we get

$$g_x(x^*, y^*) \cdot \frac{dx^*}{dc} + g_y(x^*, y^*) \frac{dy^*}{dc} = 1$$

So we have that,

$$\frac{d}{dc} f(x^*(c), y^*(c)) = \lambda^*$$

In which case,  $\lambda^*$  tells us what happens to the optimal value of the function by relaxing the constraint. Whenever,  $\lambda^* > 0$ , the optimal value increases and whenever  $\lambda^* < 0$ , it decreases.

Note: In the class, we came to the above conclusion by taking the derivative of  $L$  with respect to  $c$ . We showed that  $dL(x^*, y^*, \lambda^*)/dc = \lambda^*$ . Both approaches are equivalent because at the optimal value  $L = f$  as the constraint always binds. In the hindsight, I think the proof I outline here is slightly more intuitive.

3. (a)  $L(x, y, \omega, \lambda) = x + 2y + 3\omega + xy - y\omega + \lambda(10 - x - y - 2\omega)$

First-order conditions:

$$L_x = 1 + y - \lambda = 0$$

$$L_y = 2 + x - \omega - \lambda = 0$$

$$L_\omega = 3 - y - 2\lambda = 0$$

$$L_\lambda = 10 - x - y - 2\omega = 0$$

(b)  $L(x, y, \omega, \lambda) = x^2 + 2xy + y\omega^2 + \lambda(24 - 2x - y - \omega^2) + \mu(8 - x - \omega)$

First-order conditions:

$$L_x = 2x + 2y - 2\lambda - \mu = 0$$

$$L_y = 2x + \omega^2 - \lambda = 0$$

$$L_\omega = 2y\omega - 2\omega\lambda - \mu = 0$$

$$L_\lambda = 24 - 2x - y - \omega^2 = 0$$

$$L_\mu = 8 - x - \omega = 0$$

4.  $L(x, y, \lambda) = f(x, y) + \lambda(-G(x, y))$

First-order conditions:

$$L_x = f_x - \lambda G_x = 0$$

$$L_y = f_y - \lambda G_y = 0$$

$$L_\lambda = -G(x, y) = 0$$